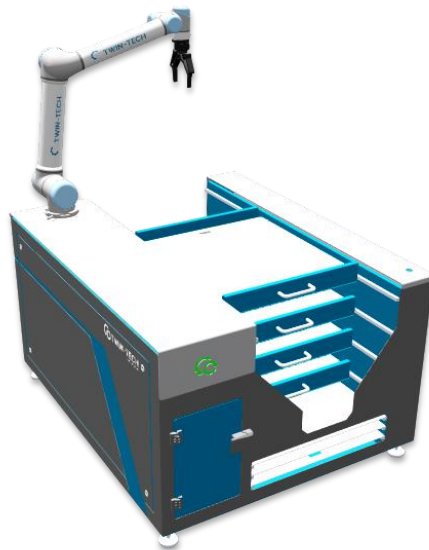


## Quotation Cobostand: Machine Loading



**Name:** Clietn Client  
**Company:** TESTML1  
**Telephone:** 2348309809  
**Email:** f.tieleman@twin-tech.nl

**Quote Number:** \QCCS230809095649

**Quotation date:** 9/8/2023

This quotation contains an offer for a full cobot stand. This offer contains all aspects of engineering, design and setup required to make the cobot ready for use.

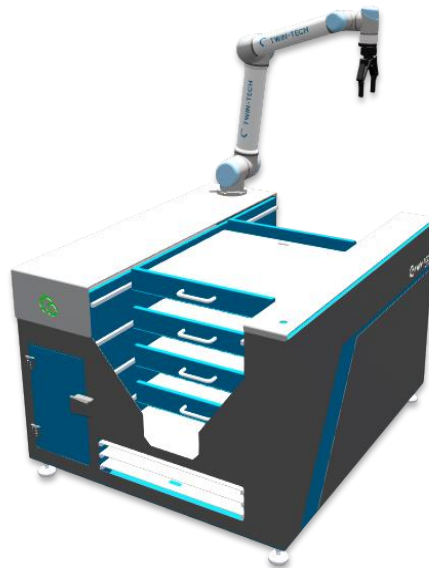
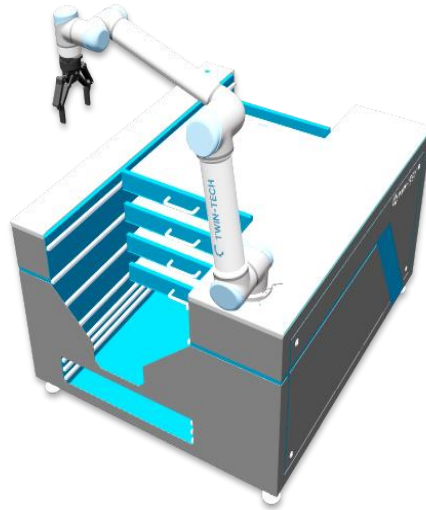
### Specifications and options

Below, an overview of the chosen options and values are shown. These values represent the key parameters of the system and were chosen by client during configuration.

<i>Options</i>	<i>Chosen parameters</i>
<i>Weight Product (kg)</i>	8
<i>Shape Product</i>	Block
<i>Material Product</i>	Aluminium
<i>Description* Product</i>	Aluminium Block
<i>Height Product(mm)</i>	20
<i>Length Product(mm)</i>	150
<i>Width Product(mm)</i>	50
<i>Diameter Product(mm)</i>	10
<i>Arm Selection</i>	UR10
<i>Gripper Type</i>	Robotiq Mechanical Precision
<i>Software Packages</i>	Machineloadng pack,
<i>Delivery</i>	Client Custom Implementation (No installation included)

## Visualization of designed system

\*Note that these renders are simplified representations of the full system.



### List of materials

Below, an overview of the components used are shown. Prices per component are listed.

NR	BESCHRIJVING	AANTAL	PRIJS
<b>1</b>	<b>Cobotstand</b>	1	€ 18965
1.1	Machine Loading stand	1	
<b>2</b>	<b>Cobot arm UR10</b>	1	€ 38340
<b>3</b>	<b>Robotiq Mechanical Precision Gripper</b>	1	€ 4575
3.1	Gripper Base	1	
3.2	Pneumatic driving systems	1	
3.3	Gripper Teeth	4	
<b>4</b>	<b>Software</b>		€ 3750
<b>Total (excl. VAT (BTW))</b>			<b>€ 72263</b>
<b>Total (incl. VAT (BTW))</b>			<b>€ 87438.23</b>

### Conditions

Conditions that hold for this quotation:

- Deposit: 50% of total valuation
- Terms and Conditions of Twin Tech Engineering are applied to this quotation.

Kind regards,

**Twin-Tech Engineering B.V.**  
**Jaargetijdeweg 4**  
**7532SX Enschede**

Jur Mourits  
*General director*